

Math 2010 Week 6

Defn Let $\Omega \subseteq \mathbb{R}^n$ be open, $f: \Omega \rightarrow \mathbb{R}$

Let $r \geq 0$. f is called a C^r function if

all partial derivatives of f up to order r

exist and are continuous on Ω

f is called a C^∞ function if it is C^r

for any $r \geq 0$

eg ① f is C^0 if it is continuous

② $f(x,y)$ is C^2 if

$f, f_x, f_y, f_{xx}, f_{xy}, f_{yx}, f_{yy}$

exist and are continuous

Examples of C^∞ function

Polynomials, Rational functions,

Exponential, Logarithm, Trigonometric functions

and their sum/difference/product/quotient/compositions

eg. $e^{x^2-y} \sin \frac{x}{y}$

Generalization of Clairaut's thm

If f is C^r on an open set $\Omega \subseteq \mathbb{R}^n$,

then the order of differentiation does not matter

for all partial derivatives up to order r .

eg If $f(x,y,z)$ is C^3 , then

$$f_{xz} = f_{zx}, \quad f_{xyz} = f_{yzx} = f_{zyx}$$

$$f_{xxy} = f_{xyx} = f_{yxx}$$

Differentiability

1 variable case revisited

$f: \mathbb{R} \rightarrow \mathbb{R}$ is differentiable at a if

$$f'(a) = \lim_{x \rightarrow a} \frac{f(x) - f(a)}{x - a} \text{ exists}$$

Multivariable case: $f: \mathbb{R}^n \rightarrow \mathbb{R}$, $\vec{a} \in \mathbb{R}^n$

Same definition?

$$\lim_{\vec{x} \rightarrow \vec{a}} \frac{f(\vec{x}) - f(\vec{a})}{\vec{x} - \vec{a}} \leftarrow \mathbb{R} \quad \checkmark$$

$\underbrace{\hspace{10em}}_{\leftarrow \mathbb{R}^n} \quad \times$

Doesn't make sense to divide by a vector

Need another way to define differentiability

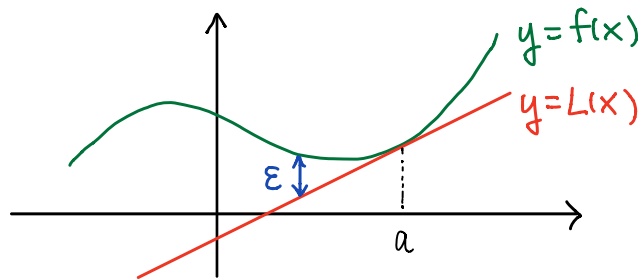
How? In terms of linear approximation and error.

Linear Approximation for $f(x)$

Suppose $f: \mathbb{R} \rightarrow \mathbb{R}$ is differentiable at a . Then

$$f(x) \approx L(x) := f(a) + f'(a)(x - a)$$

$L(x)$ is the "best" linear function (deg ≤ 1 polynomial) to approximate $f(x)$ near a



Tangent at a = "Best" line to approximate $y = f(x)$ near a

Rmk In linear algebra, linear function/map means $L(\vec{x} + \vec{y}) = L(\vec{x}) + L(\vec{y})$ and $L(c\vec{x}) = cL(\vec{x})$

In particular, $L(\vec{0}) = \vec{0}$. The $L(x)$ defined above may not be linear in this sense.

Error of approximation

$$\begin{aligned}\varepsilon(x) &= f(x) - L(x) \\ &= f(x) - f(a) - \underbrace{f'(a)(x-a)}_{\Delta x}\end{aligned}$$

Note

$$\frac{\varepsilon(x)}{x-a} = \frac{f(x) - f(a)}{x-a} - f'(a)$$

$$\begin{aligned}\lim_{x \rightarrow a} \frac{\varepsilon(x)}{x-a} &= \lim_{x \rightarrow a} \frac{f(x) - f(a)}{x-a} - f'(a) \\ &= f'(a) - f'(a) = 0\end{aligned}$$

Equivalently

$$\lim_{x \rightarrow a} \frac{|\varepsilon(x)|}{|x-a|} = 0$$

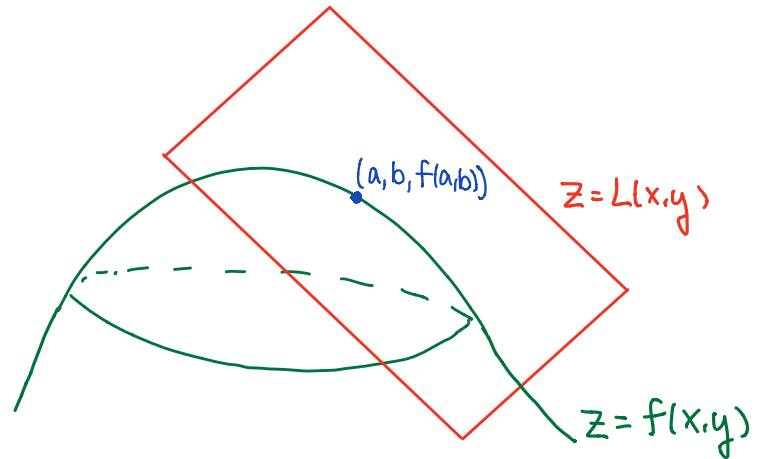
Error is small compared to $\vec{x} - \vec{a}$

In higher dim, graph of $f(\vec{x})$ should be approximated by higher dim linear objects. (eg. Tangent plane of $z=f(x,y)$)

eg Suppose $f: \mathbb{R}^2 \rightarrow \mathbb{R}$, $f_x(a,b)$, $f_y(a,b)$ exist.

Try to approximate $f(x,y)$ near (a,b) :

$$f(x,y) \approx \underbrace{f(a,b)}_{\text{value at } (a,b)} + \underbrace{f_x(a,b)}_{\text{slope in } x\text{-direction}} \underbrace{(x-a)}_{\Delta x} + \underbrace{f_y(a,b)}_{\text{slope in } y\text{-direction}} \underbrace{(y-b)}_{\Delta y}$$



Defn Let $\Omega \subseteq \mathbb{R}^n$ be open, $\vec{a} = (a_1, a_2, \dots, a_n) \in \Omega$

$f: \Omega \rightarrow \mathbb{R}$ is said to be differentiable at \vec{a} if

① All partial derivatives $\frac{\partial f}{\partial x_i}(\vec{a})$ exist for $i=1, 2, \dots, n$.

② In the linear approximation for $f(\vec{x})$ at \vec{a} ,

$$f(\vec{x}) = f(\vec{a}) + \sum_{i=1}^n \frac{\partial f}{\partial x_i}(\vec{a})(x_i - a_i) + \varepsilon(\vec{x})$$

$L(\vec{x}) =$ Linear approximation
of $f(\vec{x})$ at \vec{a} error

the error term $\varepsilon(\vec{x})$ satisfies

$$\lim_{\vec{x} \rightarrow \vec{a}} \frac{\varepsilon(\vec{x})}{\|\vec{x} - \vec{a}\|} = 0$$

A differentiable function is one which can be well approximated by a linear function locally

Rmk

$$L(\vec{x}) = f(\vec{a}) + \sum_{i=1}^n \underbrace{\frac{\partial f}{\partial x_i}(\vec{a})}_{\text{slope of } f \text{ in } x_i\text{-direction at } \vec{a}} \underbrace{(x_i - a_i)}_{\Delta x_i}$$

Note

① $L(\vec{x})$ is a $\text{deg} \leq 1$ polynomial

② $L(\vec{a}) = f(\vec{a})$

③ $\frac{\partial L}{\partial x_i}(\vec{a}) = \frac{\partial f}{\partial x_i}(\vec{a})$

$y = L(\vec{x})$ is a n -plane tangent to

$y = f(\vec{x})$ at $\vec{x} = \vec{a}$

eg1 $f(x,y) = x^2y$

- ① Show that f is differentiable at $(1,2)$
- ② Approximate $f(1.1, 1.9)$ using linearization
- ③ Find tangent plane of $z=f(x,y)$ at $(1,2,2)$

Sol ① $\frac{\partial f}{\partial x} = 2xy$ $\frac{\partial f}{\partial y} = x^2$

$\frac{\partial f}{\partial x}(1,2) = 4$ $\frac{\partial f}{\partial y}(1,2) = 1$

\therefore The linearization at $(1,2)$ is

$$L(x,y) = f(1,2) + \frac{\partial f}{\partial x}(1,2)(x-1) + \frac{\partial f}{\partial y}(1,2)(y-2)$$

$$= 2 + 4(x-1) + (y-2)$$

with error term

$$E(x,y) = f(x,y) - L(x,y)$$

$$= x^2y - 2 - 4(x-1) - (y-2)$$

$$\lim_{(x,y) \rightarrow (1,2)} \frac{E(x,y)}{\|(x,y) - (1,2)\|}$$

$$= \lim_{(x,y) \rightarrow (1,2)} \frac{x^2y - 2 - 4(x-1) - (y-2)}{\sqrt{(x-1)^2 + (y-2)^2}} \quad \begin{array}{l} \text{let } x-1=h \\ y-2=k \end{array}$$

$$= \lim_{(h,k) \rightarrow (0,0)} \frac{(1+h)^2(2+k) - 2 - 4h - k}{\sqrt{h^2 + k^2}}$$

$$= \lim_{(h,k) \rightarrow (0,0)} \frac{h^2k + 2hk + 2h^2}{\sqrt{h^2 + k^2}} \quad \begin{array}{l} \text{let } h = r \cos \theta \\ k = r \sin \theta \end{array}$$

$$= \lim_{r \rightarrow 0} \frac{r^3 \cos^2 \theta \sin \theta + 2r^2 \cos \theta \sin \theta + 2r^2 \cos^2 \theta}{r}$$

$$= \lim_{r \rightarrow 0} r^2 \cos^2 \theta \sin \theta + 2r \cos \theta \sin \theta + 2r \cos^2 \theta$$

$$= 0 \quad \text{by Sandwich theorem}$$

$\therefore f$ is differentiable at $(1,2)$

$$\begin{aligned} \textcircled{2} f(1.1, 1.9) &\approx L(1.1, 1.9) \\ &= 2 + 4(1.1 - 1) + (1.9 - 2) \\ &= 2 + 0.4 + (-0.1) \\ &= 2.3 \end{aligned}$$

Compare: $f(1.1, 1.9) = 2.299$

$\textcircled{3}$ Tangent at $(1, 2, 2)$ is

$$\begin{aligned} z &= L(x, y) \\ &= 2 + 4(x - 1) + (y - 2) \end{aligned}$$

$$z = -4 + 4x + y$$

eg 2 Is $f(x, y) = \sqrt{|xy|}$
differentiable at $(0, 0)$?

$$\text{Sol } \frac{\partial f}{\partial x}(0, 0) = \lim_{h \rightarrow 0} \frac{f(h, 0) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{0 - 0}{h} = 0$$

$$\text{Similarly } \frac{\partial f}{\partial y}(0, 0) = 0$$

$$\begin{aligned} \therefore L(x, y) &= f(0, 0) + \frac{\partial f}{\partial x}(0, 0)(x - 0) + \frac{\partial f}{\partial y}(0, 0)(y - 0) \\ &= 0 + 0 + 0 \end{aligned}$$

$\therefore L(x, y) \equiv 0$ is the zero function!

$$\text{Error: } \varepsilon(x, y) = f(x, y) - L(x, y) = \sqrt{|xy|}$$

$$\begin{aligned} \lim_{(x, y) \rightarrow (0, 0)} \frac{\varepsilon(x, y)}{\|(x, y) - (0, 0)\|} &= \lim_{(x, y) \rightarrow (0, 0)} \frac{\sqrt{|xy|}}{\sqrt{x^2 + y^2}} \\ &= \lim_{r \rightarrow 0} \frac{\sqrt{|r^2 \cos \theta \sin \theta|}}{r} \\ &= \lim_{r \rightarrow 0} \sqrt{|\cos \theta \sin \theta|} \quad \text{DNE} \end{aligned}$$

$\therefore f$ is not differentiable at $(0, 0)$

\nearrow different values
at $\theta = 0, \frac{\pi}{4}$

Rmk In last example, $f(x,y) = \sqrt{|xy|}$, $L(x,y) \equiv 0$

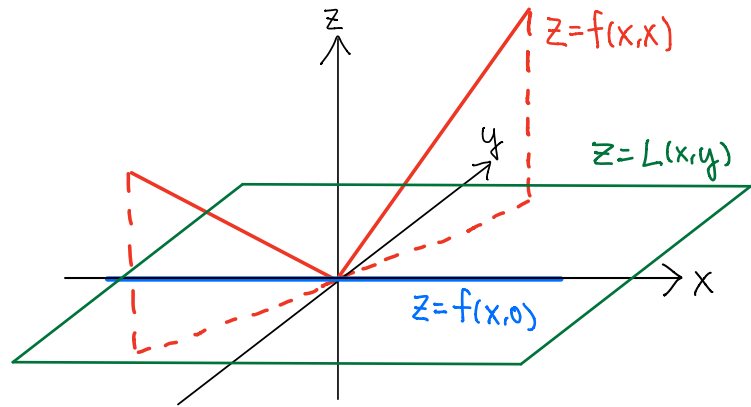
Along the line $y = mx$, $f(x, mx) = \sqrt{|mx^2|} = \sqrt{|m|}|x|$

Along x-axis ($m=0$)

$f(x,0) = 0 = L(x,0)$ (Good approximation)

Along $y=x$ ($m=1$)

$f(x,x) = |x|$, $L(x,x) = 0$ (Bad approximation)



In general, our $L(\vec{x})$ is defined using $\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n}$ (Derivatives on coordinate directions)

Differentiability: Information on coordinate directions $\left(\frac{\partial f}{\partial x_i}\right)$

can tell information on every direction

← A strong condition!

